

Finding Equilibrium Points

Alejandro Jofré, U. Chile, Santiago

R.T. Rockafellar, U. Washington, Seattle

Roger J-B Wets, U. California, Davis

Collaborators - Contributors

- ◆ Adib Bagh, Univ. California, Davis
- ◆ Sergio Lucero, Univ. California, Davis
- ◆ Michael Ferris, Univ. of Wisconsin
 - S. Robinson, J.-S. Pang, D. Ralph, ...
 - T. Munson, S. Dirkse, ...
- ◆ Hedy Attouch, Univ. de Montpellier

Further readings

- ◆ Jofré, A. & R. Wets, *Variational convergence of bivariate functions: theoretical foundations*. To appear in *Mathematical Programming* (2006).
- ◆ Jofré, A., R.T. Rockafellar R.T & R. Wets. *Variational Inequalities and economic equilibrium*. To appear in *Math. Operation Research* (2006?)
- ◆ Jofré, A., RT. Rockafellar & R. Wets, *A variational inequality scheme for determining an economic equilibrium of classical or extended type*. In "Variational analysis and applications", 553--577, *Nonconvex Optim. Appl.*, 79, Springer, New York, 2005.
- ◆ Jofré, A. & R. Wets, *Continuity properties of Walras equilibrium points. Stochastic equilibrium problems in economics and game theory*. *Annals of Operations Research*, 114 (2002), 229--243.
- ◆ S. P. Dirkse and M. C. Ferris. *The PATH solver: A non-monotone stabilization scheme for mixed complementarity problems*. *Optimization Methods and Software*, 5:123-156, 1995.

I. Walras Equilibrium Model

Deterministic
Pure Exchange model

Pure Exchange: Walras

agent's problem: Agents: $a \in \mathcal{A} \mid \mathcal{A} \mid$ finite "large"

$\bar{c}_a \in \arg \max u_a(c)$ so that $\langle p, c \rangle \leq \langle p, e_a \rangle$, $c \in C_a$

e_a : endowment of agent a , $e_a \in \text{int } C_a$

u_a : utility of agent a , concave, usc

$C_a \rightarrow \mathbb{R}$, $C_a \subset \mathbb{R}^n$ (survival set) convex

market clearing: $s(p) = \sum_{a \in \mathcal{A}} (e_a - \bar{c}_a)$ excess supply

equilibrium price: $\bar{p} \in \Delta$ such that $s(\bar{p}) \geq 0$

Δ unit simplex

The Walrasian

$$W(p, q) = \langle q, s(p) \rangle, \quad W : \Delta \times \Delta \rightarrow \mathbb{R}$$

\bar{p} equilibrium price

$$\Leftrightarrow \bar{p} \in \arg \max_p (\inf_q W(p, q)) \ \& \ s(\bar{p}) \geq 0$$

Properties of W :

continuous in p ($e_a \in \text{int } C_a$, ' a -inf-compact') **usc**

linear in q , Δ compact **convex**

$$W(p, p) \geq 0, \quad \forall p \in \Delta$$

i.e., W is a Ky Fan function

Ky Fan functions & inequality

◆ $K : B \times B \rightarrow \mathbb{R}$ is a Ky Fan function if

(a) $\forall y : x \mapsto K(x, y)$ usc

(b) $\forall x : y \mapsto K(x, y)$ convex

◆ **Theorem.** K Ky Fan fcn, $\text{dom } K = B \times B$, B compact

$\Rightarrow \text{argmax-inf } K \neq \emptyset$

if $K(x, x) \geq 0$ on $\text{dom } K$, $\bar{x} \in \text{argmax-inf } K$

$\Rightarrow \inf_y K(\bar{x}, y) \geq 0$.

◆ The Walrasian is a Ky Fan function
yields existence of equilibrium price.

II. Numerical Strategies

- Augmented Lagrangian
- Path Solver

Augmented Walrasian

◆ Augmented Walrasian:

$$\bar{p} \in \operatorname{argmax}\text{-inf } W$$

$$\cong \text{ saddle point } (\bar{p}, \bar{q}) \text{ of } \tilde{W}_r$$

$$\tilde{W}_r(p, q) = \inf_z \{ W(p, z) \mid \|z - q\| \leq r \},$$

$\|\cdot\|$ an appropriate norm ($|\cdot|_\infty$ e.g.)

from Variational Analysis

◆ Properties: \tilde{W}_r is usc in p , convex, lsc in (q, r)
non-increasing in r

◆ Saddle-points: $\sup_{p \in \Delta} \left(\inf_{q \in \Delta} W(p, q) \right) =$

$$\sup_{p \in \Delta} \left(\inf_{q \in \Delta, r \in \mathbb{R}_+} \tilde{W}_r(p, q) \right) = \inf_{q \in \Delta, r \in \mathbb{R}_+} \left(\sup_{p \in \Delta} \tilde{W}_r(p, q) \right)$$

argument similar to augmented Lagrangian

Iterations

$$W(p, q) = \langle q, s(p) \rangle \text{ on } \Delta \times \Delta$$

$$\tilde{W}_r(p, q) = \inf_z \{ W(p, z) \mid \|z - q\| \leq r \}$$

$$q^{k+1} = \arg \min_{q \in \Delta} \left[\min_z \langle z, s(p^k) \rangle \mid \|z - q\| \leq r_k \right]$$

minimizing a linear form on a ball

reduces to finding the smallest element of $s(p^k)$

$$p^{k+1} = \arg \max_{p \in \Delta} \left[\min_z \langle z, s(p) \rangle \mid \|z - q^{k+1}\| \leq r_{k+1} \right]$$

as $r_k \nearrow \infty$, $p^k \rightarrow \bar{p}$ (Walras equilibrium point)

Test: Demand functions

- ◆ Cobb-Douglas utility function (usc):

$$u_a(c) = \gamma_a \prod_{l=1}^n c_l^{\beta_a^l} \quad \text{with} \quad \sum_{l=1}^n \beta_a^l = 1, \beta_a^l \geq 0$$

- ◆ budget constraint: $\sum_l p_l c_l \leq \sum_l p_l e_a^l$

- ◆ demand: $\bar{c}_a^l(p) = (\beta_a^l / p_l) \left(\sum_k p_k e_a^k \right), l = 1, \dots, n$

experiments: 10 agents, 150 goods (blink!)

Variational Inequality I

$$\max_c u_a(c) \text{ so that } \langle p, c \rangle \leq \langle p, e_a \rangle, c \in C_a. \quad a \in \mathcal{A}$$
$$\sum_a (e_a - c_a) = s(p) \geq 0.$$



KKT-Optimality Conditions & Market Clearing:

$\bar{c}_a \in C_a$ optimal $\Leftrightarrow \exists \lambda_a \geq 0$ (linear constraint)

(a) $\langle p, e_a - \bar{c}_a \rangle \geq 0$ (feasibility)

(b) $\lambda_a (\langle p, e_a - \bar{c}_a \rangle) = 0$ (compl. slackness)

(c) $\nabla u_a(\bar{c}_a) - \lambda_a p = 0$ ($e_a \in \text{int } C_a$)

(d) $\sum_a (e_a - \bar{c}_a) = 0$ (market clearing)

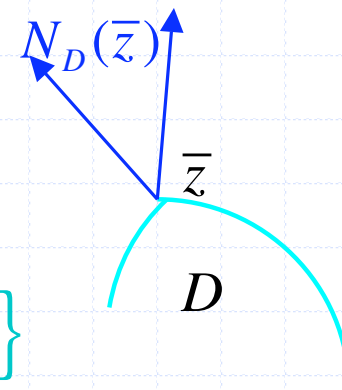
Variational Inequality II

$$\max_c u_a(c) \text{ so that } \langle p, c \rangle \leq \langle p, e_a \rangle, c \in C_a, \forall a$$

$$\sum_a (e_a - c_a) = s(p) \geq 0.$$



$$N_D(\bar{z}) = \{v \mid \langle v, z - \bar{z} \rangle \leq 0, \forall z \in D\}$$



$$G(p, (c_a), (\lambda_a)) = \left[\sum_a (e_a - c_a); (\lambda_a p - \nabla u_a(c_a)); \langle p, e_a - c_a \rangle \right]$$

$$D = \Delta \times \left(\prod_a C_a \right) \times \left(\prod_a \mathbb{R}_+ \right)$$

$$-G(\bar{p}, (\bar{c}_a), (\bar{\lambda}_a)) \in N_D(\bar{p}, (\bar{c}_a), (\bar{\lambda}_a))$$

D (unfortunately) is unbounded

bounding D : “solvable” V.I.

from D to \hat{D} bounded with
explicit bounds derived via duality (finite # goods)
(global bound for C_a , κ_a depends on 'var'(u_a))

$$-G(\bar{p}, (\bar{c}_a), (\bar{\lambda}_a)) \in N_{\hat{D}}(\bar{p}, (\bar{c}_a), (\bar{\lambda}_a))$$

$$\hat{D} = \Delta \times \left(\prod_a \hat{C}_a \right) \times \left(\prod_a [0, \kappa_a] \right)$$

Polyhedral case: efficient algorithmic procedures

Path Solver .. *(by Ferris & all)*

$$-G(\bar{z}) \in N_D(\bar{z}), \quad \bar{z} = (\bar{p}, (\bar{c}_a), (\bar{\lambda}_a))$$

$$D = \Delta \times \left(\prod_a C_a \right) \times \left(\prod_a \mathbb{R}_+ \right) = \{z \mid Az \geq b\}$$

Complementarity problem:

$$-G(z) = A^T y, \quad y \geq 0, \quad Az - b \perp y$$

with $K = \mathbb{R}^N \times \mathbb{R}_+^M$:

$$(z, y) \in K, \quad H(z, y) \in -K^*, \quad (z, y) \perp H(z, y)$$

$$H(z, y) = \begin{bmatrix} G(z) + A^T y \\ Az \end{bmatrix} - \begin{pmatrix} 0 \\ b \end{pmatrix}$$

Equivalent non-smooth mapping

◆ $0 = H(\text{prj}_K(z, y)) + (z, y) - \text{prj}_K(z, y)$

◆ with simplified $K = \mathbb{R}_+^N$:

(CP) $0 \leq x \perp F(x) \geq 0$ Complementarity Problem

(NS) $0 = F(x_+) + x - x_+$ Nonlinear system

◆ \bar{x} sol'n (CP) $\Rightarrow \tilde{x}$ sol'n (NS):

$$\tilde{x}_i = \bar{x}_i \text{ if } F_i(\bar{x}) = 0, \quad \tilde{x}_i = -F_i(\bar{x}_i) \text{ if } F_i(\bar{x}) > 0$$

\tilde{x} sol'n (NS) $\Rightarrow \tilde{x}_+$ sol'n (CP):

$$\tilde{x}_+ \geq 0, F(\tilde{x}_+) = \tilde{x}_+ - \tilde{x} \geq 0 \ \& \ \tilde{x}_+ \perp \tilde{x}_+ - \tilde{x}$$

PATH Solver: $x = (z, y), x_+ = \text{prj}_K(x, y)$

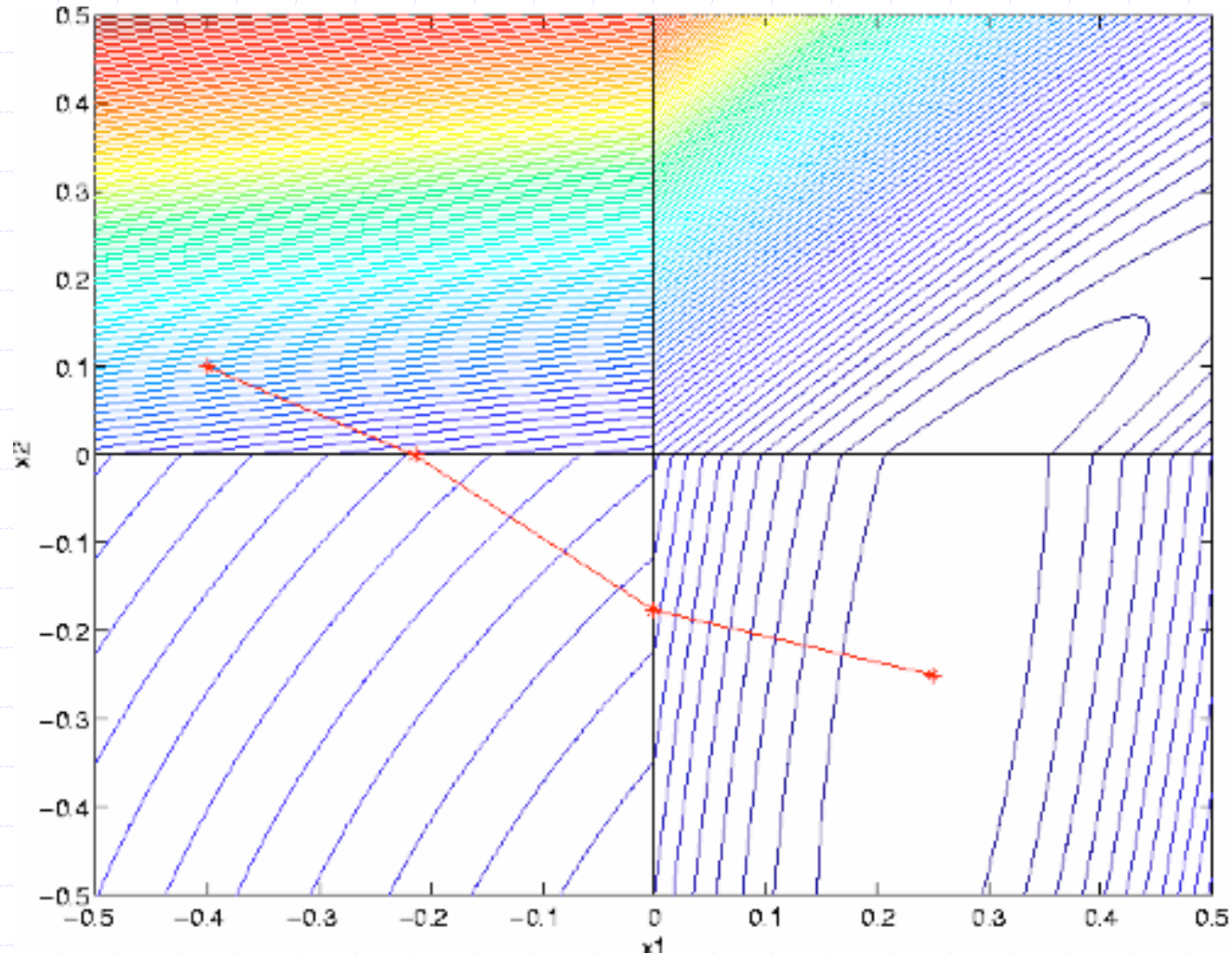
- ◆ PATH: Newton method based on non-smooth normal mapping:

$$H(x_+) + x - x_+$$

- ◆ Newton point: solution of piecewise linearization:

$$H(x_+^k) + \langle \nabla H(x_+^k), x_+ - x_+^k \rangle + x - x_+ = 0$$

The "Newton" step



with PATH Solver (experimental)

- ◆ Economy: (5 goods)
 - Skilled & unskilled workers
 - Businesses: Basic goods & leisure
 - Banker: bonds (riskless), 2 stocks
- ◆ 2-stages, solved under # of scenarios
- ◆ utilities: CSE-functions (gen. Cobb-Douglas)
 - Utility in stage 2 assigned to financial instruments
 - only used for transfer in stage 1
- ◆ so far: mostly calibration
numerically: `blink' (5000 iterations).

III. Continuity, Stability Issues

equilibrium points
solutions of V.I., ...

Variational Convergence

◆ solutions of optimization problems

- $\arg \min f^v \rightarrow \arg \min f$: epi-convergence
- $\arg \max f^v \rightarrow \arg \max f$: hypo-convergence

◆ stability of saddle points

- saddle pts $K^v \rightarrow$ saddle pts K : epi/hypo-convergence

◆ stability of maxinf points

- $\max \inf K^v \rightarrow \max \inf K$: lopsided convergence (tightly)

Walras Equilibrium points

- ◆ $\forall a \in \mathcal{A}: \bar{c}_a(p) \in \arg \max_{c_a} \left\{ u_a(c_a) \mid \langle p, c_a \rangle \leq \langle p, e_a \rangle \right\}$
- ◆ $s(p) = \sum_a (e_a - d_a(\bar{c}_a))$ excess supply
- ◆ find $\bar{p} \in \Delta$ (unit simplex) so that $s(\bar{p}) \geq 0$
- ◆ **Walrasian:** $W(p, q) = \langle q, s(p) \rangle$ Ky Fan fcn
- ◆ $\bar{p} \in \arg \max\text{-inf } W \Leftrightarrow s(\bar{p}) \geq 0$
- ◆ **conditions:** $e_a \in \text{int dom } u_a$, "globally compact"
- ◆ **Convergence:** $u_a^v \xrightarrow{\text{hypo}} u_a, e_a^v \rightarrow e_a \Rightarrow$
 W^v converge lopsided tightly to W

Variational Inequalities

◆ $C \subset \mathbb{R}^n$ non-empty, convex

◆ $G : C \rightarrow \mathbb{R}^n$ continuous

◆ find $\bar{u} \in C$ such that $-G(\bar{u}) \in N_C(\bar{u})$

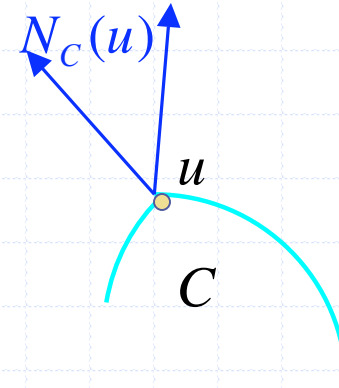
where $v \in N_C(\bar{u}) \Leftrightarrow \langle v, u - \bar{u} \rangle \leq 0, \forall u \in C$

◆ with $K(u, v) = \langle G(u), v - u \rangle$ on $\text{dom } K = C \times C$

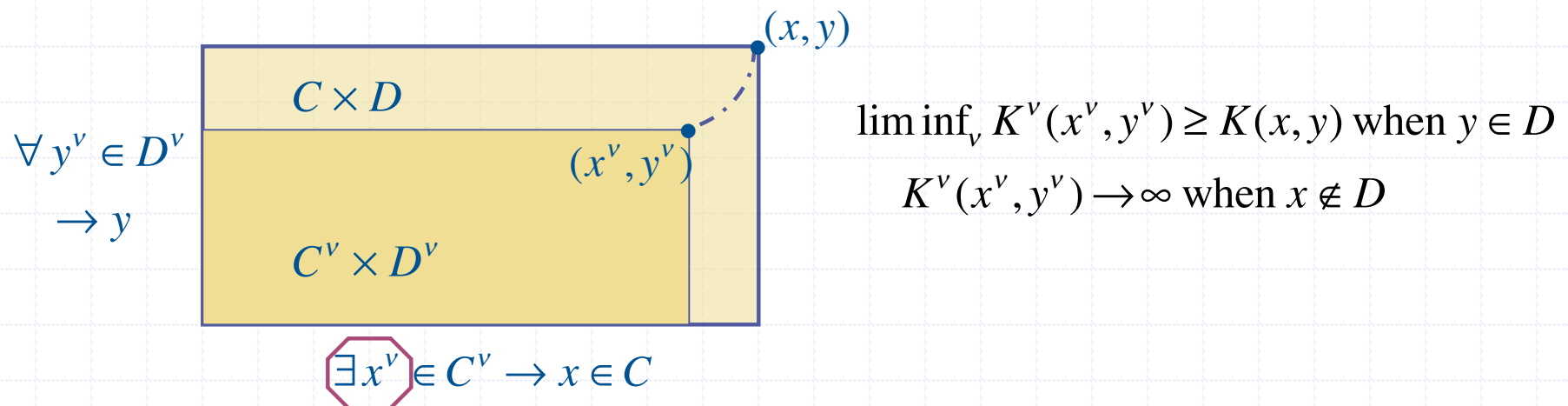
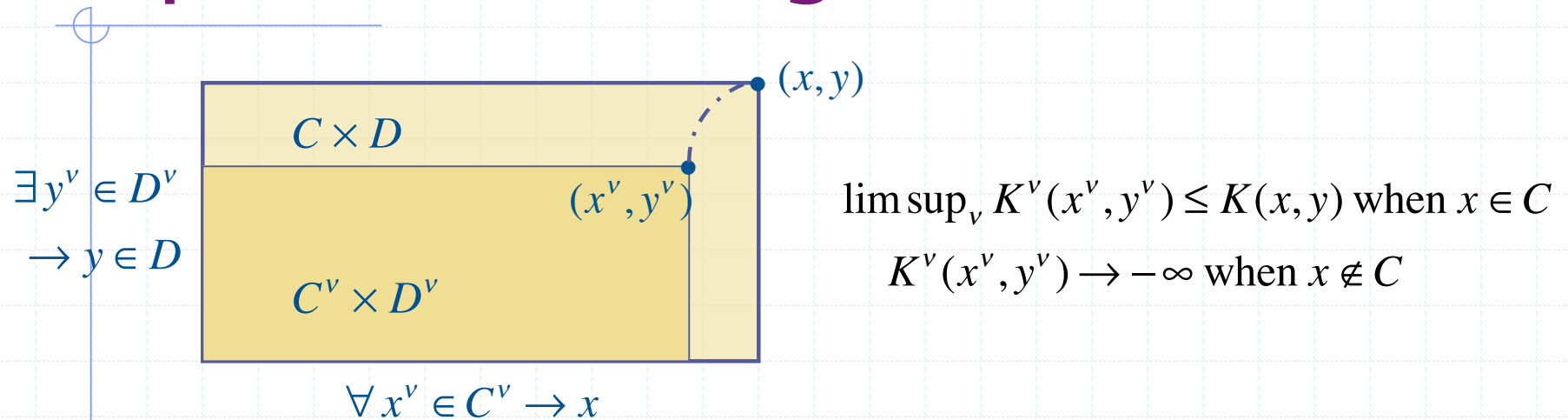
⇒ K is a Ky Fan function, $K(u, u) \geq 0$.

◆ Find

$\bar{u} \in \arg \max\text{-inf } K(\cdot, \cdot)$ so that $K(\bar{u}, \cdot) \geq 0$



Lopsided convergence: definition



Lopsided tightly

◆ $K_{C^v \times D^v}^v \xrightarrow{\text{lop-tightly}} K_{C \times D}$ if $K_{C^v \times D^v}^v \xrightarrow{\text{lop}} K_{C \times D}$ &

(b) $\forall x \in C, \exists x^v \rightarrow x, \forall y^v \in D^v$ and $y^v \rightarrow y$:

$$\liminf K^v(x^v, y^v) \geq K(x, y) \text{ if } y \in D$$

$$K^v(x^v, y^v) \rightarrow \infty \text{ if } y \notin D$$

but also $\forall \varepsilon > 0, \exists B_\varepsilon$ compact (depends on $x^v \rightarrow x$):

$$\inf_{B_\varepsilon \cap D^v} K^v(x^v, \cdot) \leq \inf_{D^v} K^v(x^v, \cdot) + \varepsilon, \forall v \geq v_\varepsilon$$

◆ THM. $K_{C^v \times D^v}^v \rightarrow K_{C \times D}$ lopsided tightly, \bar{x} cluster point of

$$\{x^v \in \arg \max\text{-inf } K_{C^v \times D^v}^v\}_{v \in \mathbb{N}} \Rightarrow \bar{x} \in \arg \max\text{-inf } K_{C \times D}$$

Proof

$$\diamond K_{C^v \times D^v}^v \xrightarrow{\text{lop-tightly}} K_{C \times D}$$

$$\text{Let } g^v = \inf_{y \in D^v} K^v(\cdot, y), \quad g = \inf_{y \in D} K(\cdot, y).$$

$$\Rightarrow g^v \xrightarrow{\text{hypo}} g \text{ when } \begin{cases} C_g^v = \{x \in C^v \mid g^v(x) > -\infty\} \\ C_g = \{x \in C \mid g(x) > -\infty\} \end{cases} \neq \emptyset$$

\diamond then apply

$$g_{C^v}^v \xrightarrow{\text{hypo}} g_C, \quad x^v \in \arg \max_{C^v} g^v, \quad x^{v_k} \rightarrow \bar{x} \in C \Rightarrow \bar{x} \in \arg \max_C g$$

Extending Ky Fan's inequality



$K^v \rightarrow K$ lopsided

K^v Ky Fan $\Rightarrow K$ Ky Fan



& when $\arg \max\text{-inf } K^v \neq \emptyset$

if $\bar{x} \in \text{cluster-pts } \{\arg \max\text{-inf } K^v\}$

$\Rightarrow \bar{x} \in \arg \max\text{-inf } K$ & $K(\bar{x}, \bullet) \geq 0$



Ky Fan fcns closed under tight-lopsided

saddle fcns closed under hypo/epi-convergence

usc fcns closed under hypo-convergence